(14)   (2) If a target object is a
three-dimensional object and has a depth and
an uneven surface pattern, the appearance
(area, shape, and the like) of the
object changes in different directions.

(15)   (3) If a target object is not a
perfectly rigid object (e.g., a man
wearing clothing), the shape of the object
changes at each time point.

(16)   (4) If a portion of a background and a
portion of a target object have
the same color or luminance, the same color or
luminance portion of the target
object is not detected as a changing area
while the target object passes
through the same color or luminance portion of
the background.

(17)   In the states wherein corresponding
changing areas are not necessarily
detected at each time point as described
above, since corresponding changing
areas may not be present, moving vectors may
not be obtained. Therefore, the
block association processing scheme may not
properly function. If the block
association processing scheme fails or does
not properly function as described
above, serious problems are posed when it is
applied to a monitoring system
(display monitoring system).

(18)   In order to solve the above-described
problems, a tracking means capable

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(94)   (4) In the above embodiments, changes are considered only in terms of
brightness.   However, a method of detecting changes on the basis of changes in
color or texture may be simply used depending on an application. If it is
known in advance that a target object has a specific color, a change can be
reliably detected by detecting a change in color or by assemblying a plurality
of change detections. In this case, depending on a target object, a change can
be properly detected only by certain processing. In such a case, the method
used in the change detection should be transferred to the tracking step so that
tracking processing is also performed in consideration of the used method, thus
improving the reliability of processing.

(95)   (5) In the above embodiments, only the sizes of changing areas are taken
into consideration to determine which one of the areas is to be tracked.
However, if a changing area is selected in consideration of information about
the shapes of changing areas in addition to their sizes, a target can be more
reliably selected. Since the contour of a still object tends to be mistaken
for a changing portion due to the difference between the contour and the
background, the following processing may be additionally performed: removing
edges such as the contour mentioned above, or neglecting changes occurring at

unit. In this case, it serves as a module for
tracking an object and
extracting its contour.

(109)   Modifications of the candidate
extraction processing performed by the
candidate extracting section 440 will be
described below.

(110)   (1) Only information relating to the
moving path of each tracking unit,
such as position and speed information of each
tracking unit within an image,
is used to the estimation function used for
candidate extraction processing.
However, feature amounts of, e.g., **color** and
shape, obtained from the tracking
area of each tracking unit may be added to the
information. Assume that a
plurality of tracking units are concurrently
tracking body portions of an
intruder in red clothing. If the process for
determining the identity of the
intruder is additionally performed upon
extraction of color information from
the tracking area of each tracking unit, a
candidate can be easily extracted by
associating the information from the tracking
unit.

(111)   (2) The estimation function used for
calculating the association
strengths between the tracking units in
candidate extraction processing may be
replaced with the process for extracting a
candidate for a moving object by
using knowledge associated with the positions

associating the information from the tracking unit.

(111) (2) The estimation function used for calculating the association
strengths between the tracking units in candidate extraction processing may be replaced with the process for extracting a candidate for a moving object by
using knowledge associated with the positions and speeds of tracking units,
attribute values such as the colors and shapes of changing areas which are
being tracked, and the preset shape and movement information of an intruder.

(112) An example of this processing will be described below. Processing
modules are prepared. Each module compares the respective information
described above between two tracking units and converts the comparison result
into numerical values indicating whether the compared information are close to
each other (i.e., moving objects resemble each other or the same moving object
is tracked). Output results from the respective processing modules may be
simply added together. Alternatively, the priorities of the respective
information are determined, and a weighted sum obtained by weighting in
accordance with the priorities is used as an association strength. For
example, by using information associated with the shape of an intruder, the
probability of obtaining an accurate result

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processing.

(113) (3) Each candidate list formed by the candidate extracting section 440
need not be constituted by only a group of tracking units but may include the
overall position information of the candidates and attribute values such as
color and shape information obtained from areas to which the tracking units are
assigned. In this case, feature extraction processing is performed in addition
to candidate extraction processing so that when candidate are extracted by the
candidate extraction processing, feature information can be simultaneously
extracted from areas in an image in which the candidates exists. The extracted
feature information is then added to the candidate information to form a
candidate list. If additional attribute values are included in candidate data,
association processing is facilitated by adding the process for determining the
similarity of attribute values to the process for associating candidates in the
result interpreting section 450. In addition, the reliability of the
association processing result is increased. The feature extraction processing
need not be included in the candidate extraction processing but may be
performed parallel as independent processing so that the feature extraction
processing can be sequentially performed in response to requests from the
candidate extraction processing.